

NAG Toolbox for MATLAB

c05pc

1 Purpose

c05pc is a comprehensive function to find a solution of a system of nonlinear equations by a modification of the Powell hybrid method. You must provide the Jacobian.

2 Syntax

```
[x, fvec, fjac, diag, nfev, njev, r, qtf, ifail] = c05pc(fcn, x, diag,
mode, nprint, lr, 'n', n, 'xtol', xtol, 'maxfev', maxfev, 'factor',
factor)
```

3 Description

The system of equations is defined as:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad \text{for } i = 1, 2, \dots, n.$$

c05pc is based on the MINPACK routine HYBRJ (see Moré *et al.* 1980). It chooses the correction at each step as a convex combination of the Newton and scaled gradient directions. Under reasonable conditions this guarantees global convergence for starting points far from the solution and a fast rate of convergence. The Jacobian is updated by the rank-1 method of Broyden. At the starting point the Jacobian is calculated, but it is not recalculated until the rank-1 method fails to produce satisfactory progress. For more details see Powell 1970.

4 References

Moré J J, Garbow B S and Hillstom K E 1980 User guide for MINPACK-1 *Technical Report ANL-80-74* Argonne National Laboratory

Powell M J D 1970 A hybrid method for nonlinear algebraic equations *Numerical Methods for Nonlinear Algebraic Equations* (ed P Rabinowitz) Gordon and Breach

5 Parameters

5.1 Compulsory Input Parameters

1: **fcn** – string containing name of m-file

Depending upon the value of **iflag**, **fcn** must either return the values of the functions f_i at a point x or return the Jacobian at x .

Its specification is:

```
[fvec, fjac, iflag] = fcn(n, x, fvec, fjac, ldfjac, iflag)
```

Input Parameters

1: **n** – int32 scalar

n , the number of equations.

2: **x(n)** – double array

The components of the point x at which the functions or the Jacobian must be evaluated.

- 3: **fvec(n) – double array**
 If **iflag** = 0 or 2, **fvec** contains the function values $f_i(x)$ and must not be changed.
 If **iflag** = 1 on entry, **fvec** must contain the function values $f_i(x)$ (unless **iflag** is set to a negative value by **fcn**).
- 4: **fjac(ldfjac,n) – double array**
ldfjac, the first dimension of the array, must be at least **n**.
 If **iflag** = 0 or 1, **fjac** contains the value of $\frac{\partial f_i}{\partial x_j}$ at the point x , for $i, j = 1, 2, \dots, n$, and must not be changed.
 If **iflag** = 2 on entry, **fjac**(i, j) must contain the value of $\frac{\partial f_i}{\partial x_j}$ at the point x , for $i, j = 1, 2, \dots, n$, (unless **iflag** is set to a negative value by **fcn**).
- 5: **ldfjac – int32 scalar**
- 6: **iflag – int32 scalar**
iflag = 0, 1 or 2.
iflag = 0
 x and **fvec** are available for printing (see **nprint**).
iflag = 1
 fvec is to be updated.
iflag = 2
 fjac is to be updated.
- In general, **iflag** should not be reset by **fcn**. If, however, you wish to terminate execution (perhaps because some illegal point **x** has been reached), then **iflag** should be set to a negative integer. This value will be returned through **ifail**.

Output Parameters

- 1: **fvec(n) – double array**
 If **iflag** = 0 or 2, **fvec** contains the function values $f_i(x)$ and must not be changed.
 If **iflag** = 1 on entry, **fvec** must contain the function values $f_i(x)$ (unless **iflag** is set to a negative value by **fcn**).
- 2: **fjac(ldfjac,n) – double array**
 If **iflag** = 0 or 1, **fjac** contains the value of $\frac{\partial f_i}{\partial x_j}$ at the point x , for $i, j = 1, 2, \dots, n$, and must not be changed.
 If **iflag** = 2 on entry, **fjac**(i, j) must contain the value of $\frac{\partial f_i}{\partial x_j}$ at the point x , for $i, j = 1, 2, \dots, n$, (unless **iflag** is set to a negative value by **fcn**).
- 3: **iflag – int32 scalar**
iflag = 0, 1 or 2.
iflag = 0
 x and **fvec** are available for printing (see **nprint**).

iflag = 1

fvec is to be updated.

iflag = 2

fjac is to be updated.

In general, **iflag** should not be reset by **fcn**. If, however, you wish to terminate execution (perhaps because some illegal point **x** has been reached), then **iflag** should be set to a negative integer. This value will be returned through **ifail**.

2: **x(n)** – double array

An initial guess at the solution vector.

3: **diag(n)** – double array

If **mode** = 2, **diag** must contain multiplicative scale factors for the variables.

Constraint: **diag**(*i*) > 0.0, for *i* = 1, 2, ..., *n*.

4: **mode** – int32 scalar

Indicates whether or not you have provided scaling factors in **diag**. If **mode** = 2 the scaling must have been specified in **diag**. Otherwise, the variables will be scaled internally.

5: **nprint** – int32 scalar

Indicates whether special calls to the user-supplied (sub)program **fcn**, with **iflag** set to 0, are to be made for printing purposes.

nprint ≤ 0

No calls are made.

nprint > 0

user-supplied (sub)program **fcn** is called at the beginning of the first iteration, every **nprint** iterations thereafter and immediately prior to the return from c05pc.

6: **lr** – int32 scalar

Constraint: **lr** ≥ **n** × (**n** + 1)/2.

5.2 Optional Input Parameters

1: **n** – int32 scalar

Default: The dimension of the arrays **x**, **fvec**, **diag**, **fjac**, **qtf**. (An error is raised if these dimensions are not equal.)

n, the number of equations.

Constraint: **n** > 0.

2: **xtol** – double scalar

The accuracy in **x** to which the solution is required.

Suggested value: the square root of the *machine precision*.

Default: $\sqrt{\epsilon}$

Constraint: **xtol** ≥ 0.0.

3: **maxfev** – int32 scalar

The maximum number of calls to the user-supplied (sub)program **fcn** with **iflag** $\neq 0$. **c05pc** will exit with **ifail** = 2, if, at the end of an iteration, the number of calls to **fcn** exceeds **maxfev**.

Suggested value: **maxfev** = $100 \times (\mathbf{n} + 1)$.

Default: $100 \times (\mathbf{n} + 1)$

Constraint: **maxfev** > 0.

4: **factor** – double scalar

A quantity to be used in determining the initial step bound. In most cases, **factor** should lie between 0.1 and 100.0. (The step bound is **factor** \times $\|\mathbf{diag} \times \mathbf{x}\|_2$ if this is nonzero; otherwise the bound is **factor**.)

Suggested value: **factor** = 100.0.

Default: 100.0

Constraint: **factor** > 0.0.

5.3 Input Parameters Omitted from the MATLAB Interface

ldfjac, w

5.4 Output Parameters1: **x(n)** – double array

The final estimate of the solution vector.

2: **fvec(n)** – double array

The function values at the final point, **x**.

3: **fjac(ldfjac,n)** – double array

The orthogonal matrix Q produced by the QR factorization of the final approximate Jacobian.

4: **diag(n)** – double array

The scale factors actually used (computed internally if **mode** $\neq 2$).

5: **nfev** – int32 scalar

The number of calls made to user-supplied (sub)program **fcn** to evaluate the functions.

6: **njev** – int32 scalar

The number of calls made to user-supplied (sub)program **fcn** to evaluate the Jacobian.

7: **r(lr)** – double array

The upper triangular matrix R produced by the QR factorization of the final approximate Jacobian, stored row-wise.

8: **qtf(n)** – double array

The vector $Q^T f$.

9: **ifail** – int32 scalar

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail < 0

This indicates an exit from c05pc because you have set **iflag** negative in the user-supplied (sub)program **fcn**. The value of **ifail** will be the same as your setting of **iflag**.

ifail = 1

On entry, **n** ≤ 0,
or **xtol** < 0.0,
or **maxfev** ≤ 0,
or **factor** ≤ 0.0,
or **ldfjac** < **n**,
or **lr** < **n** × (**n** + 1)/2,
or **mode** = 2 and **diag**(*i*) ≤ 0.0 for some *i*, *i* = 1, 2, ..., **n**.

ifail = 2

There have been **maxfev** evaluations of user-supplied (sub)program **fcn** to evaluate the functions. Consider restarting the calculation from the final point held in **x**.

ifail = 3

No further improvement in the approximate solution **x** is possible; **xtol** is too small.

ifail = 4

The iteration is not making good progress, as measured by the improvement from the last five Jacobian evaluations.

ifail = 5

The iteration is not making good progress, as measured by the improvement from the last 10 iterations.

The values **ifail** = 4 and 5 may indicate that the system does not have a zero, or that the solution is very close to the origin (see Section 7). Otherwise, rerunning c05pc from a different starting point may avoid the region of difficulty.

7 Accuracy

If \hat{x} is the true solution and D denotes the diagonal matrix whose entries are defined by the array **diag**, then c05pc tries to ensure that

$$\|D \times (x - \hat{x})\|_2 \leq \mathbf{xtol} \times \|D \times \hat{x}\|_2.$$

If this condition is satisfied with **xtol** = 10^{-k} , then the larger components of Dx have *k* significant decimal digits. There is a danger that the smaller components of Dx may have large relative errors, but the fast rate of convergence of c05pc usually avoids this possibility.

If **xtol** is less than *machine precision* and the above test is satisfied with the *machine precision* in place of **xtol**, then the function exits with **ifail** = 3.

Note: this convergence test is based purely on relative error, and may not indicate convergence if the solution is very close to the origin.

The test assumes that the functions and the Jacobian are coded consistently and that the functions are reasonably well behaved. If these conditions are not satisfied, then c05pc may incorrectly indicate convergence. The coding of the Jacobian can be checked using c05za. If the Jacobian is coded correctly, then the validity of the answer can be checked by rerunning c05pc with a tighter tolerance.

8 Further Comments

The time required by c05pc to solve a given problem depends on n , the behaviour of the functions, the accuracy requested and the starting point. The number of arithmetic operations executed by c05pc is about $11.5 \times n^2$ to process each evaluation of the functions and about $1.3 \times n^3$ to process each evaluation of the Jacobian. Unless user-supplied (sub)program **fcn** can be evaluated quickly, the timing of c05pc will be strongly influenced by the time spent in **fcn**.

Ideally the problem should be scaled so that, at the solution, the function values are of comparable magnitude.

9 Example

```
c05pc_fcn.m

function [fvec, fjac, iflag] = c05pc_fcn(n,x,fvec,fjac,ldfjac,iflag)

    if (iflag ~= 2)
        for k = 1:n
            fvec(k) = (3.0-2.0*x(k))*x(k) + 1.0;
            if (k > 1)
                fvec(k) = fvec(k) - x(k-1);
            end
            if (k < n)
                fvec(k) = fvec(k) - 2.0*x(k+1);
            end
        end
    else
        fjac = zeros(n,n);
        for k = 1:n
            fjac(k,k) = 3.0 - 4.0*x(k);
            if (k > 1)
                fjac(k,k-1) = -1.0;
            end
            if (k < n)
                fjac(k,k+1) = -2.0;
            end
        end
    end
end
```

```
x = [-1;
      -1;
      -1;
      -1;
      -1;
      -1;
      -1;
      -1;
      -1];
diag = [1;
        1;
        1;
        1;
        1;
        1;
        1;
        1;
        1];
mode = int32(2);
nprint = int32(0);
lr = int32(45);
[xOut, fvec, fjac, diagOut, nfev, njev, r, qtf, ifail] = ...
    c05pc('c05pc_fcn', x, diag, mode, nprint, lr)
```

```

xOut =
  -0.5707
  -0.6816
  -0.7017
  -0.7042
  -0.7014
  -0.6919
  -0.6658
  -0.5960
  -0.4164
fvec =
  1.0e-08 *
    0.6560
   -0.4175
   -0.5193
   -0.2396
    0.2022
    0.4818
    0.2579
   -0.3884
   -0.0136
fjac =
  Columns 1 through 7
   -0.9691   -0.2148   -0.0209    0.0470    0.0611    0.0339   -0.0188
    0.2268   -0.9561   -0.1558    0.0078    0.0423    0.0328   -0.0064
   -0.0174    0.1584   -0.9720   -0.1533   -0.0206    0.0090    0.0087
   -0.0478   -0.0482    0.1554   -0.9653   -0.1728   -0.0306    0.0139
   -0.0414   -0.0486   -0.0103    0.1910   -0.9579   -0.1638   -0.0068
   -0.0072   -0.0143   -0.0058    0.0102    0.1882   -0.9588   -0.1373
    0.0361    0.0408    0.0197    0.0011   -0.0011    0.1731   -0.9455
    0.0591    0.0849    0.0606    0.0302    0.0175    0.0320    0.2366
    0.0164    0.0304    0.0474    0.0704    0.1040    0.1402    0.1748
  Columns 8 through 9
   -0.0678   -0.0471
   -0.0621   -0.0582
   -0.0254   -0.0720
    0.0072   -0.0918
    0.0214   -0.1198
   -0.0024   -0.1614
   -0.1429   -0.2288
   -0.8900   -0.3679
    0.4218   -0.8676
diagOut =
    1
    1
    1
    1
    1
    1
    1
    1
    1
    1
nfev =
      11
njev =
      1
r =
  -5.9002
   4.1274
  -0.4204
  -0.4522
  -0.5225
  -0.3437
  -0.0653
   0.0185
  -0.5519
  -6.0563
   3.2570
  -0.5570
  -0.3043

```

```
-0.2274
-0.0452
 0.1224
-0.3490
-6.4766
 3.2423
-0.2317
-0.0327
-0.0923
 0.0258
 0.0501
-6.3881
 3.5140
-0.1806
-0.1332
-0.1071
 0.4337
-6.2931
 3.4096
-0.4194
-0.1511
 0.7698
-6.4309
 3.1398
-0.3188
 0.9972
-6.5080
 3.4679
 0.7938
-6.0582
 4.8522
-3.8733
qtf =
 1.0e-07 *
-0.3574
 0.0823
 0.2291
 0.1836
 0.0005
-0.2262
-0.2399
 0.1980
 0.0074
ifail =
      0
```